

HARVIS: smart assistant for Non-Stabilized Approaches

Alexandre Duchevet, Théo De La Hogue, Jean-Paul Imbert

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Within the Cleansky 2 framework, the HARVIS project aims to identifty how cognitive computing algorithms implemented in a digital assistant could support the decision making process of a single pilot in complex situation at 2035+ horizon.







Go-around prediction

SPO introduce new challenges during the final approach:

Thanks to machine learning algorithms, the assistant detects situations in which a go-around is needed.

Its training is based on the classification of over 750 final approaches by 28 Commercial Air Transport pilots.





CLASSIFICATION BY EXPERT PILOTS

▶ No flight parameters monitoring by another crew member.

▷ No workload sharing,

making the single pilot more vulnerable to task interruptions.

▶ No possibility to discuss

opinions for complex decision

Dataset filtering could permit to SPEED tailor the assistant to a specific airline or, even more, to a specific **PITCH**

parameters could improve the relevancy of go-around predictions.

Extension to more flight

GO-AROUND PREDICTION MODULE

LOC

VERTICAL SPEED

SLOPE

GO AROUND

Pitch, Roll, Ground Speed, Vertical Speed, Localizer Deviation, Glide Slope Deviation,

"ioo

Intelligent callouts

Thanks to an eye tracking device, callouts are emited only when pilots do not pay attention to a flight parameter deviation.

▶ Monitoring the situation awareness throught the gaze position is limited. Broadening pilot monitoring with other physiological parameters could be interesting.



making.





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Monitoring