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Wind Mill Pattern Optimization using Evolutionary Algorithms

Charlie Vanaret
ENAC*, IRIT†
7 av Ed Belin
31055 Toulouse Cedex 5,
France
vanaret@recherche.enac.fr

Nicolas Durand
ENAC, IRIT
7 av Ed Belin
31055 Toulouse Cedex 5,
France
durand@recherche.enac.fr

Jean-Marc Alliot
IRIT
118 route de Narbonne
31062 Toulouse Cedex 9,
France
jean-marc.alliot@irit.fr

ABSTRACT

When designing a wind farm layout, we can reduce the number of variables by optimizing a pattern instead of considering the position of each turbine. In this paper we show that when reducing the problem to only two variables defining a grid, we can gain up to 3% of energy output on simple examples of wind farms dealing with many turbines (up to 1000) while dramatically reducing computation time. To achieve these results, we compared both a genetic algorithm and a differential evolution algorithm to previous results from the literature. These preliminary results should be extended to examples involving non-rectangular farm layouts and wind distributions that may require pattern deformation variables in order to increase solution diversity.

Categories and Subject Descriptors

J.6 [Computer-Aided Engineering]: Computer-aided design; D.2.2 [Software Engineering]: Design Tools and Techniques—*Computer-aided software engineering*

Keywords

wind energy, wind farm layout, optimization

1. INTRODUCTION

In the last 15 years, there has been growing interest and investment in renewable energy. Wind power capacity, for example, has risen from 17GW in 2000 to around 250GW in 2013, and the annual growth rate is currently between 10 and 20%. Consequently, the economic stakes and attempts to discover techniques for efficiently installing wind farms both onshore and offshore have increased dramatically; Gonzalez's recent review [2] lists almost 150 bibliographic references for the optimal wind-turbine micro-sitings problem.

*Ecole Nationale de l'Aviation Civile

†Institut de Recherche en Informatique de Toulouse

Because turbines create a wake vortex that reduces the wind flow for neighbouring units, packing as many wind turbines as possible in a given area is inefficient. There are different wake vortex models; in this paper, we use the park model described in [7] to compute these wake effects. In this model the wake effects created by all turbines j for $j \neq i$ on a turbine i changes the wind resource available to i along different directions by reducing the scale parameter c of the Weibull distribution estimated for the entire farm, which is also called the freestream wind resource. These effects depend on the relative location of the j turbines relative to i . Thus, for each turbine i , we have a parameter c_i : its computation is complex and involves wind velocity deficits $Vdef_{ij}$ that the turbine i experiences due to the influence of other turbines j , for $j \neq i$. The simple evaluation of one configuration is thus quadratic regarding the number of turbines. The algorithm we use to compute the wake effect is described in [9] and more information regarding the mathematics and the physics behind the calculation of the wake effect are in [4].

A variety of techniques have already been deployed to optimize wind farm layout but have so far proved relatively inefficient. Genetic algorithms were already used in [5], and many other evolutionary or bio inspired techniques have been tested, including cell positioning (see for example [12, 11]) or Evolutionary Strategies [4, 1]. One of the most recent approach, [10], uses CMA-ES to position 1000 turbines but takes weeks to solve the problem.

Deterministic or greedy algorithms have also been used. [9] presents a deterministic algorithm that outperforms [10]'s CMA-ES algorithm computation time and seems to be one of the best algorithms known so far.

All these algorithms, whether stochastic or deterministic, try to optimize $2n$ variable models, where the variables, x and y , define turbine position. Inversely, [6] tries to develop a model based on the optimization of regular patterns that can be described with fewer variables. GL Garrad Hassan GmbH has integrated this algorithm into WindFarmer's commercial software. Yet, even in the authors' own estimations, this approach is deemed inferior to the more global solution of optimizing individual turbine positions.

In this paper, we use [9]'s exact models and algorithms¹

¹We want to thank Sylvain Cussat-Blanc for giving us access

to show that using regular patterns optimized by an evolutionary method outperforms current evolutionary and deterministic methods not only for computation times but also for power output in large (over 200 turbines) setups. We argue that when the number of variables becomes too large, the ES gets stuck in local minima whatever the computation time thus rendering methods with less variables more efficient. To prove our point, we employ here a very simple regular pattern model using only two variables. However we also present more elaborate models that could enhance future results.

2. WIND FARM MODELING

The most general model to optimize a wind farm takes into account the coordinates of each wind mill as variables and tries to optimize energy achievement with this set of positions. For a wind farm dealing with n wind mills, the number of variables is then $2 \times n$. For large wind farms, dealing with too many variables can become challenging. Reducing the number of variables in order to simplify the problem can thus be an effective workaround. [13] have already studied mills on grids for simple cases by considering different grid types and then using a genetic algorithm to optimize them. However, they only took into account small (<60 mills) wind farms. [6] further argue that grid patterns can also optimize a wind farm's visual impact and reduce cable and access road costs. Taking for example a 100 turbine farm, they compare a stochastic layout to a regular pattern on a $5 \times 5 \text{ km}$ area, showing that the regular pattern only reduces the performance of the wind farm by 3%.

Even when dealing with the general model, defining the starting point for any optimization process can be challenging. Choosing mill positions randomly is difficult because a minimum distance between mills must be respected. For these reasons, it may be worthwhile, at least initially, to reduce the degrees of freedom in the optimization by only optimizing a simple pattern. This first pattern can then be used to create an initial starting point for another algorithm or to build an initial population for a different, population-based algorithm.

In this paper, we define a simple wind mill pattern that can be optimized with an evolutionary algorithm in order to optimize the mill positions on a field such as that presented in [9]. The mill farm pattern only depends on 2 parameters: α determines the angle of the mills alignment with the longest edge of the field. δ measures the space between two lines of mills on the longest edge of the field. If the number of mills n is fixed, we try to set the mills up as regularly as possible. In figure 1, the length of the green line gives the available distance to regularly position the mills. A mill can be positioned at each edge of the field. If \mathbf{n} is the total number of mills, \mathbf{l} is the length of the green line and \mathbf{n}_c the number of times the green line is *cut* (reaches an edge of the field), then the distance between two mills is close to $\mathbf{d} = \frac{\mathbf{l}}{(\mathbf{n} - \mathbf{n}_c)}$. When δ and α are chosen, a simple process can position the mills regularly on the field according to the distance d previously calculated.

If the field shape (see figure 1) is different and contains one to the source code of [9, 14].

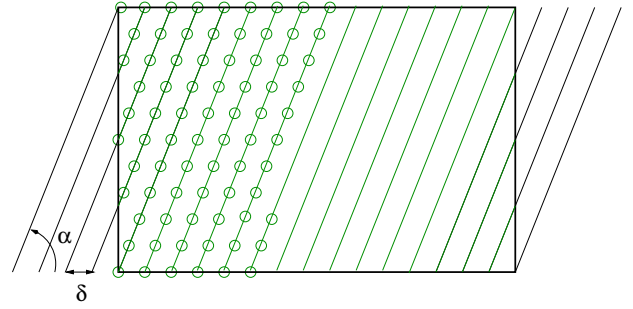


Figure 1: Wind mill field pattern modeling

or more holes (forbidden zones), we would need to adjust \mathbf{d} in order to take into account the forbidden zones and place the required number of mills on the field.

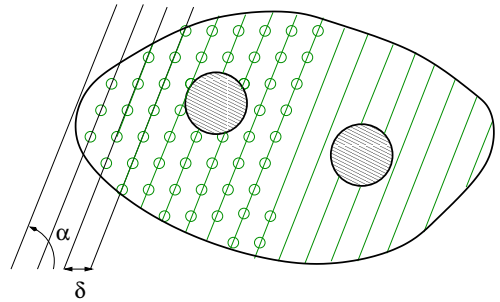


Figure 2: Wind mill field pattern modeling

3. OPTIMIZATION TOOL

We do not necessarily need an evolutionary algorithm to solve a problem dealing with only two variables. However, the modeling presented here is deliberately simple and could be made more complex in the future to take into account different scenarios. We could, for example add homothetic deformations of the pattern which would add 3 variables per deformation to the problem: two variables would represent the coordinates of the homothetic center and one variable for its ratio. We could also optimize the number of turbines itself.

The problem would still require fewer variables than the $2 \times \mathbf{n}$ of the general approach, but it could potentially involve enough variables to justify using an evolutionary approach. Because we will add these complexities in our future work, we decided to test two Evolutionary Algorithms for the current problem. The first is a Classical Genetic Algorithm described in section 3.1 and the second is a Differential Evolution approach described in section 3.2.

3.1 Genetic Algorithm

Genetic algorithms (GA) mimic the process of natural evolution in that they model operations such as inheritance, mutation, selection, and crossover [3]. Individuals gradually evolve at each generation and the population is partially replaced after crossover (with probability p_c) and mutation (with probability p_m) operations (Alg. 1).

Algorithm 1 Genetic algorithm

```
Randomly initialize each individual
Evaluate each individual
while termination criterion is not met do
  Apply scaling and sharing to the cost values
  Replicate best-fit individuals
  Apply  $p_c N$  crossovers and  $p_m N$  mutations
  Evaluate the cost of newly generated individuals
end while
Return the best individual(s) of the population
```

In the following, p_c is set to 0.6 and p_m to 0.2. N is the population size, and is set to 50. 100 generations are executed for each run.

Our implemented genetic algorithm benefits from two classic improvements: *sigma truncation scaling* and *clusterized sharing*. The selection process then operates on the image of the cost value under the scaling and sharing functions. *Scaling* aims to modify the cost values to artificially reduce or amplify gaps between individuals' cost values, thus enhancing the exploration of the search-space. *Sharing* prevents the gathering of individuals around a prevailing optimum. *Clusterized sharing* is described in [15].

3.2 Differential Evolution

Differential evolution (DE) is inspired by genetic algorithms (mutation and crossover operations) and geometric research strategies (such as the Nelder-Mead method) [8]. A single operation performing mutation and crossover is used to combine the positions of existing individuals from the population. If the new position of an individual is an improvement, it is updated in the population, otherwise the new position is simply discarded (Alg. 2).

Algorithm 2 Differential evolution algorithm

```
Randomly initialize each individual
Evaluate each individual
while termination criterion is not met do
  for each individual  $i = 1, \dots, N$  in the population do
    Pick individuals  $\mathbf{x}_a$ ,  $\mathbf{x}_b$  and  $\mathbf{x}_c$  from the population
    Compute new vector  $\mathbf{y}_i = (y_{i,1}, \dots, y_{i,n})^T$  as follows:
    for each dimension  $j \in \{1, \dots, n\}$  do
      Pick random number  $r_j \in [0, 1]$ 
      if  $j = R$  or  $r_j < CR$  then
         $y_{i,j} \leftarrow x_{a,j} + F \times (x_{b,j} - x_{c,j})$ 
      else
         $y_{i,j} \leftarrow x_{i,j}$ 
      end if
    end for
    Replace  $\mathbf{x}$  with  $\mathbf{y}$  if  $\mathbf{y}$  improves the cost value
  end for
end while
Return the best individual(s) of the population
```

\mathbf{x}_a , \mathbf{x}_b and \mathbf{x}_c are chosen at random, all distinct from each other and from \mathbf{x}_i . R is a random index $\in \{1, \dots, n\}$ ensuring that at least one component of \mathbf{y}_i differs from this of \mathbf{x}_i . N is the population size, $F \in [0, 2]$ is called the differential weight and $CR \in [0, 1]$ is the crossover probability. In the following, N is set to 50, F to 1.5 and CR to 0.0. 100 generations are executed for each run.

4. NUMERICAL RESULTS

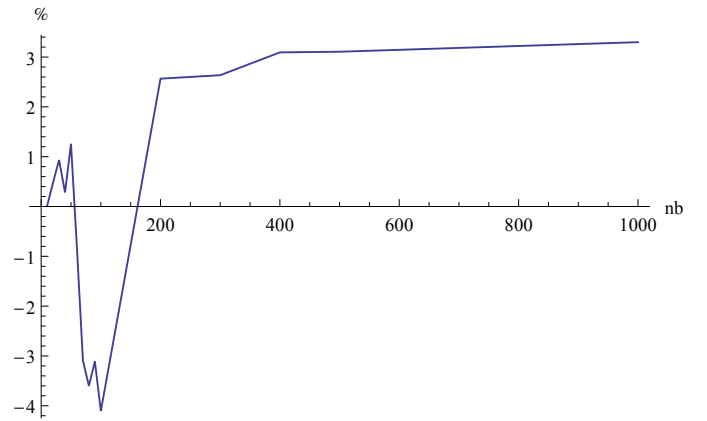


Figure 3: Comparison (in %) of DE with TDA-100k on different number of turbines.

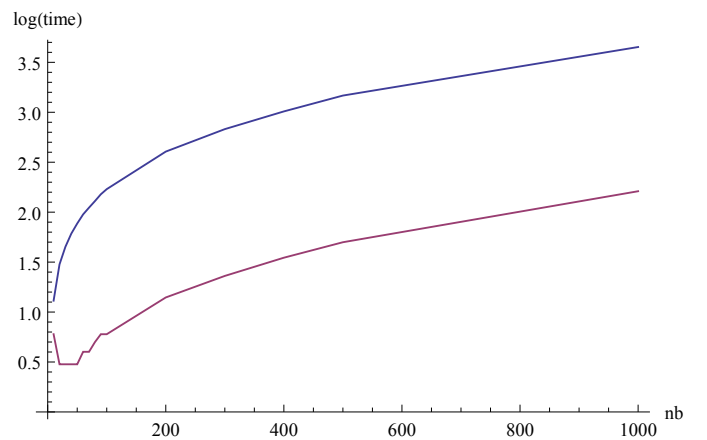


Figure 4: TDA-100k (blue) and DE (red) execution time on different number of turbines. Scale is logarithmic in $\log_{10}(\text{time})$.

In order to test our pattern modeling we used results previously published by [9] on different wind farm sizes. Several scenarios were set up with varying numbers of turbines, and varying farm sizes. For $n = 10, 20, 30, \dots, 100$ turbines, a quadratic farm of size $3\text{km} \times 3\text{km}$ was used, and for $n = 200, 300, 400, 500$ and 1000 turbines, rectangular farms of $8\text{km} \times 5\text{km}$, $10\text{km} \times 6\text{km}$, $12\text{km} \times 6\text{km}$, $14\text{km} \times 7\text{km}$ and $20\text{km} \times 10\text{km}$ were chosen.

Tables 1 and 2 compare results obtained using a Local Search algorithm proposed by Wagner in [9] to the patterns we optimized with a Genetic Algorithm(1) and a Differential Evolution Algorithm(2). These results are summarized for the DE algorithm in figures 3 and 4.

For each scenario, we executed 100 runs. In Table 1, the first columns give the size of the problem, the best and mean energy outputs in kW obtained by Wagner [9]. The computation time in minutes for the 30 runs executed by Wagner is given in the fourth column. Columns 5 and 6 give the

n	TDA 200k Max	TDA 200k Mean	time (min)	GA Max	GA Mean	GA stdev	time (min)	α <i>opt</i>	δ <i>opt</i>	gain(+) loss(-)
10	7.314e+04	7.309e+04	13	7.315e+04	7.314e+04	1.2e+01	6	810.14	0.495180	0.07%
20	1.449e+05	1.448e+05	30	1.456e+05	1.454e+05	1.5e+02	2	789.71	0.531091	0.41%
30	2.144e+05	2.135e+05	45	2.164e+05	2.162e+05	3.6e+02	2	746.27	0.038119	1.26%
40	2.806e+05	2.791e+05	61	2.814e+05	2.808e+05	1.9e+02	3	919.46	0.592378	0.61%
50	3.418e+05	3.412e+05	77	3.461e+05	3.461e+05	4.5e+00	3	745.07	0.737000	1.44%
60	4.022e+05	4.011e+05	95	3.988e+05	3.954e+05	4.7e+03	4	692.07	0.745209	-1.42
70	4.591e+05	4.555e+05	111	4.449e+05	4.443e+05	2.0e+03	5	566.51	0.726369	-2.46
80	5.108e+05	5.090e+05	129	4.925e+05	4.921e+05	9.3e+02	7	499.77	0.674266	-3.32
90	5.625e+05	5.609e+05	151	5.450e+05	5.419e+05	4.1e+03	7	431.46	0.725736	-3.39
100	6.113e+05	6.083e+05	170	5.863e+05	5.796e+05	7.2e+03	6	395.30	0.645553	-4.72
200	1.325e+06	1.323e+06	404	1.359e+06	1.359e+06	1.1e+01	16	727.00	0.688262	2.72%
300	1.973e+06	1.971e+06	678	2.025e+06	2.024e+06	1.5e+03	26	735.16	0.741059	2.69%
400	2.586e+06	2.584e+06	1020	2.666e+06	2.665e+06	4.0e+02	39	722.81	0.693413	3.13%
500	3.251e+06	3.249e+06	1470	3.352e+06	3.352e+06	3.4e+02	53	724.88	0.739885	3.17%
1000	6.454e+06	6.449e+06	4500	6.669e+06	6.668e+06	7.7e+02	166	709.31	0.694013	3.40%

Table 1: Comparison of results obtained with TDA and GA on different number of turbines (time is for 30 runs as in [9]).

n	TDA 200k Max	TDA 200k Mean	time (min)	DE Max	DE Mean	DE stdev	time (min)	α <i>opt</i>	δ <i>opt</i>	gain(+) loss(-)
10	7.314e+04	7.309e+04	13	7.315e+04	7.313e+04	1.2e+01	6	809.93	0.495069	0.05%
20	1.449e+05	1.448e+05	30	1.456e+05	1.454e+05	1.4e+02	3	790.21	0.530879	0.41%
30	2.144e+05	2.135e+05	45	2.164e+05	2.164e+05	1.8e+02	3	745.82	0.038130	1.36%
40	2.806e+05	2.791e+05	61	2.814e+05	2.809e+05	2.2e+02	3	918.81	0.591977	0.64%
50	3.418e+05	3.412e+05	77	3.461e+05	3.460e+05	3.0e+01	3	744.85	0.736872	1.41%
60	4.022e+05	4.011e+05	95	3.988e+05	3.984e+05	3.9e+02	4	691.87	0.744932	-0.67%
70	4.591e+05	4.555e+05	111	4.449e+05	4.446e+05	2.2e+02	4	566.21	0.726147	-2.39%
80	5.108e+05	5.090e+05	129	4.924e+05	4.919e+05	2.6e+02	5	499.38	0.673879	-3.36%
90	5.625e+05	5.609e+05	151	5.450e+05	5.441e+05	5.6e+02	6	431.32	0.725975	-3.00%
100	6.113e+05	6.083e+05	170	5.862e+05	5.819e+05	2.2e+03	6	395.03	0.644272	-4.34%
200	1.325e+06	1.323e+06	404	1.359e+06	1.359e+06	1.1e+02	14	727.05	0.688215	2.72%
300	1.973e+06	1.971e+06	678	2.025e+06	2.025e+06	1.2e+03	23	735.13	0.741127	2.74%
400	2.586e+06	2.584e+06	1020	2.666e+06	2.664e+06	3.3e+02	35	722.76	0.693168	3.10%
500	3.251e+06	3.249e+06	1470	3.352e+06	3.350e+06	1.9e+03	50	724.75	0.739924	3.11%
1000	6.454e+06	6.449e+06	4500	6.669e+06	6.668e+06	6.8e+02	162	709.26	0.693959	3.40%

Table 2: Comparison of results obtained with TDA and DE on different number of turbines (time is for 30 runs as in [9]).

best and mean results obtained with our pattern with the Genetic Algorithm for 100 runs. Column 7 gives the standard deviation of the results. Column 8 gives the mean time necessary for 30 runs, in order to compare the order of magnitudes with Wagner’s results. The time comparison itself is not very relevant, because the machines used are probably different, but the difference in magnitude (from 75 hours for $n = 1000$ with Wagner’s method to less than 3 hours with the GA approach) shows the impact of dealing with very few variables. Comparing the number of evaluations is much more relevant. In his paper Wagner, uses 200 000 evaluations whereas the GA we implemented required only 4000 evaluations. The last column gives the gain(+) or loss(-) obtained on the mean value found with the GA compared to Wagner’s results.

Results show that for big farms (≥ 200 turbines) using a local search algorithm is less effective than optimizing the farm pattern. Surprisingly, this is also true for small farms (≤ 50 turbines). For mid-size farms the local search algorithm presented by [9] gives better results. This is consistent with results presented by Neubert [6]: for a 100 turbine farm, they obtained a 3% loss by using a regular pattern to optimize turbine positions.

Table 2 gives the same results for the DE approach and the conclusions are similar. This tends to show that the solution found is robust to the choice of the metaheuristic used. In bold we give the best results found for the two approaches.

5. CONCLUSION

Optimizing wind farm configuration is a challenging issue for which problem modeling is critical. In this paper, we have shown that optimizing a simple pattern outperforms existing results on configurations involving a large number of turbines. The gain obtained for farms of 400 and more turbines exceeds 3%, while reducing computation time by an order of magnitude.

The modeling is deliberately simple, as this paper’s goal was to reduce as much as possible the number of variables of the general model while keeping excellent results: by reducing the size of the problem, we can focus on optimizing efficiently a small number of variables, and the loss due to the lack of generality of the model is more than compensated by a “better” optimization of the remaining variables.

There are now many directions for further research. On the one hand, this model can be complexified in order to create more elaborated shapes and to increase the variety of the solutions found. For example, we can imagine adding a number of homothetic deformations in the modeling. On the other hand these results can be used as a starting point for a single point optimization algorithm (such as simulated annealing or steepest descent) or to build a population of starting points for population based metaheuristics.

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