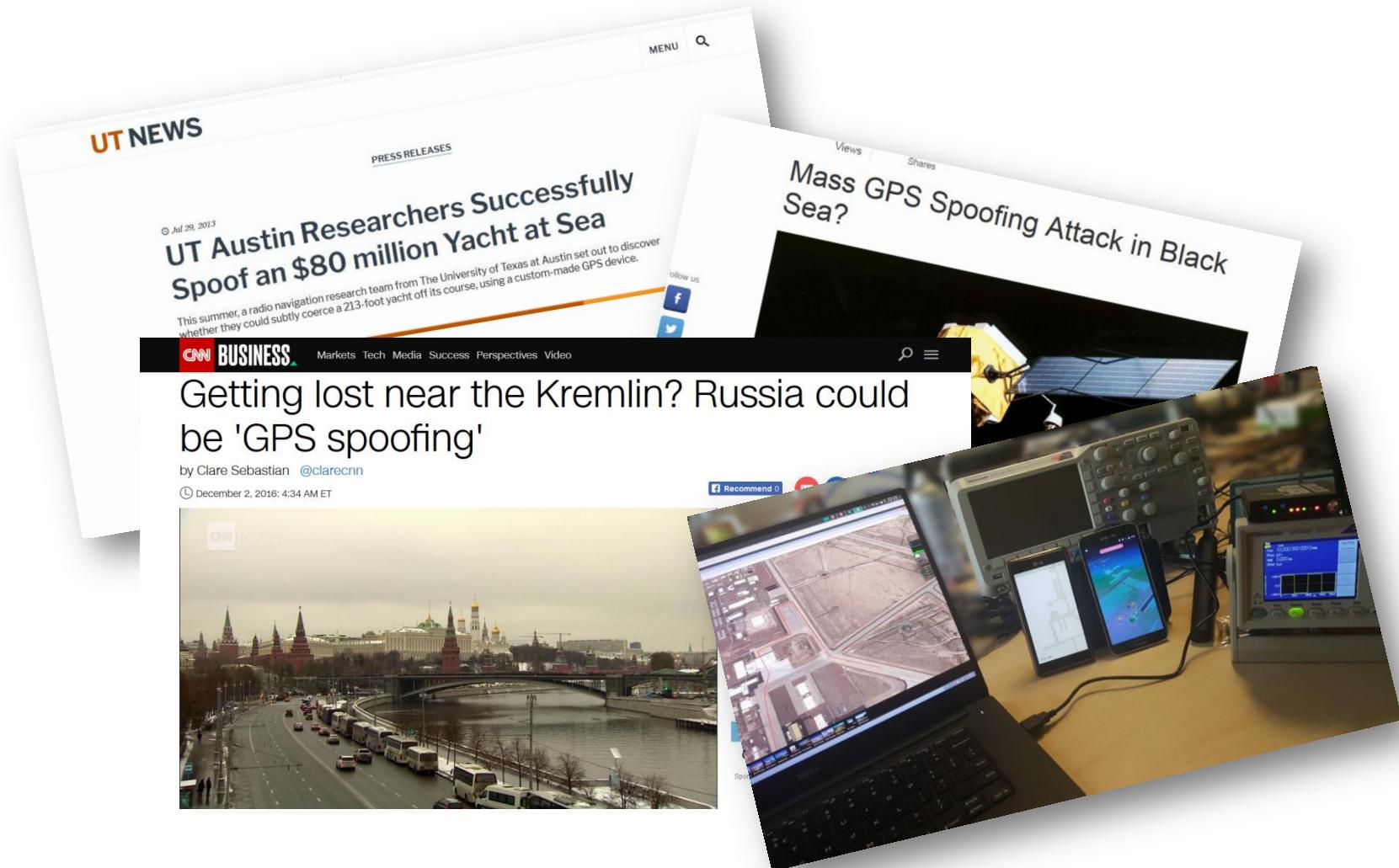

RECEIVER INDEPENDENT IMPLEMENTATION OF THE GALILEO OPEN SERVICE NAVIGATION MESSAGE AUTHENTICATION (OS-NMA)

ITSNT 2018: Navigation in Challenging Environment II

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The threat of spoofing



Need of protection

- Authentication at signal level (e.g. Galileo Public Regulated Service)



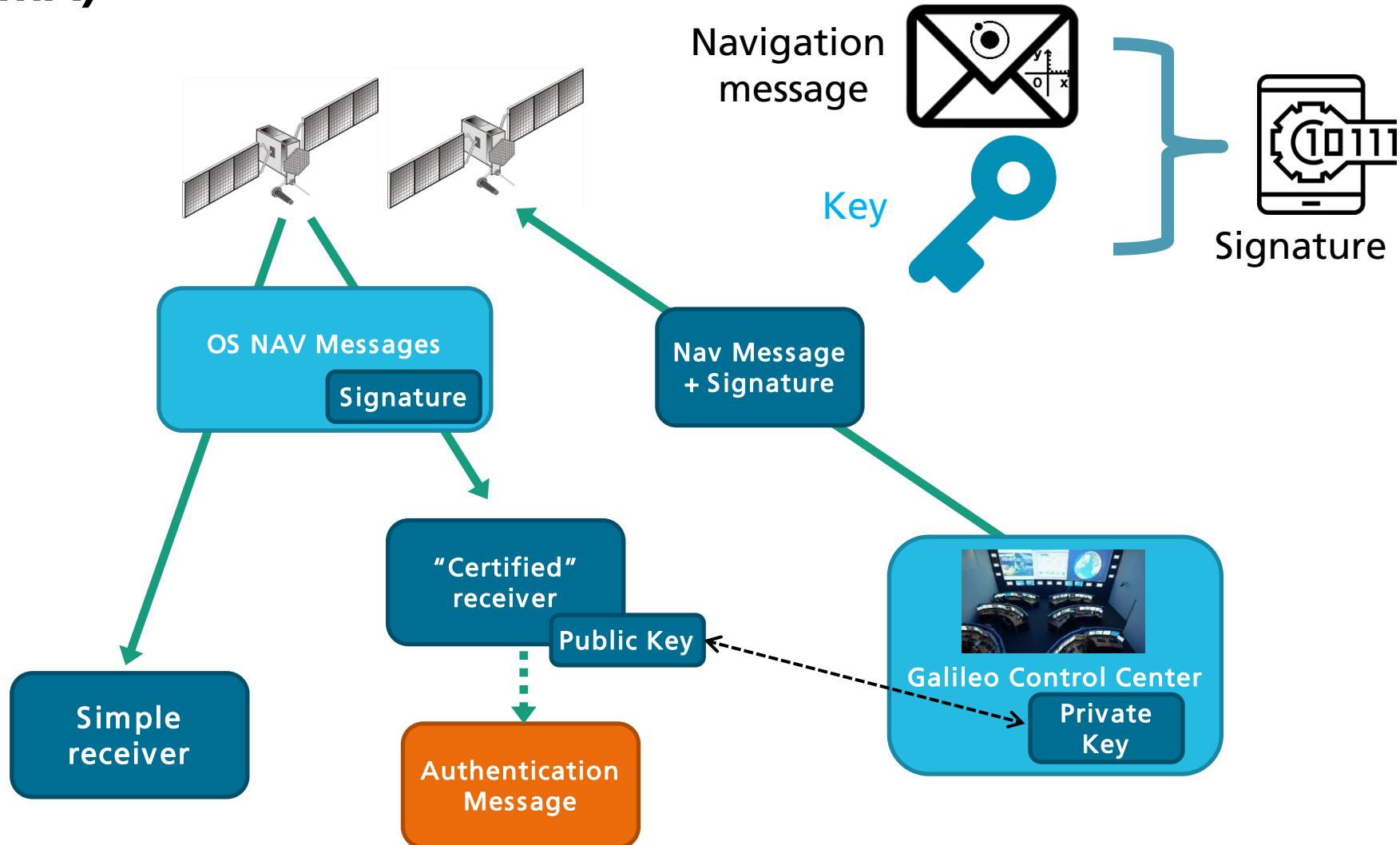
- Authentication at message level



AGENDA

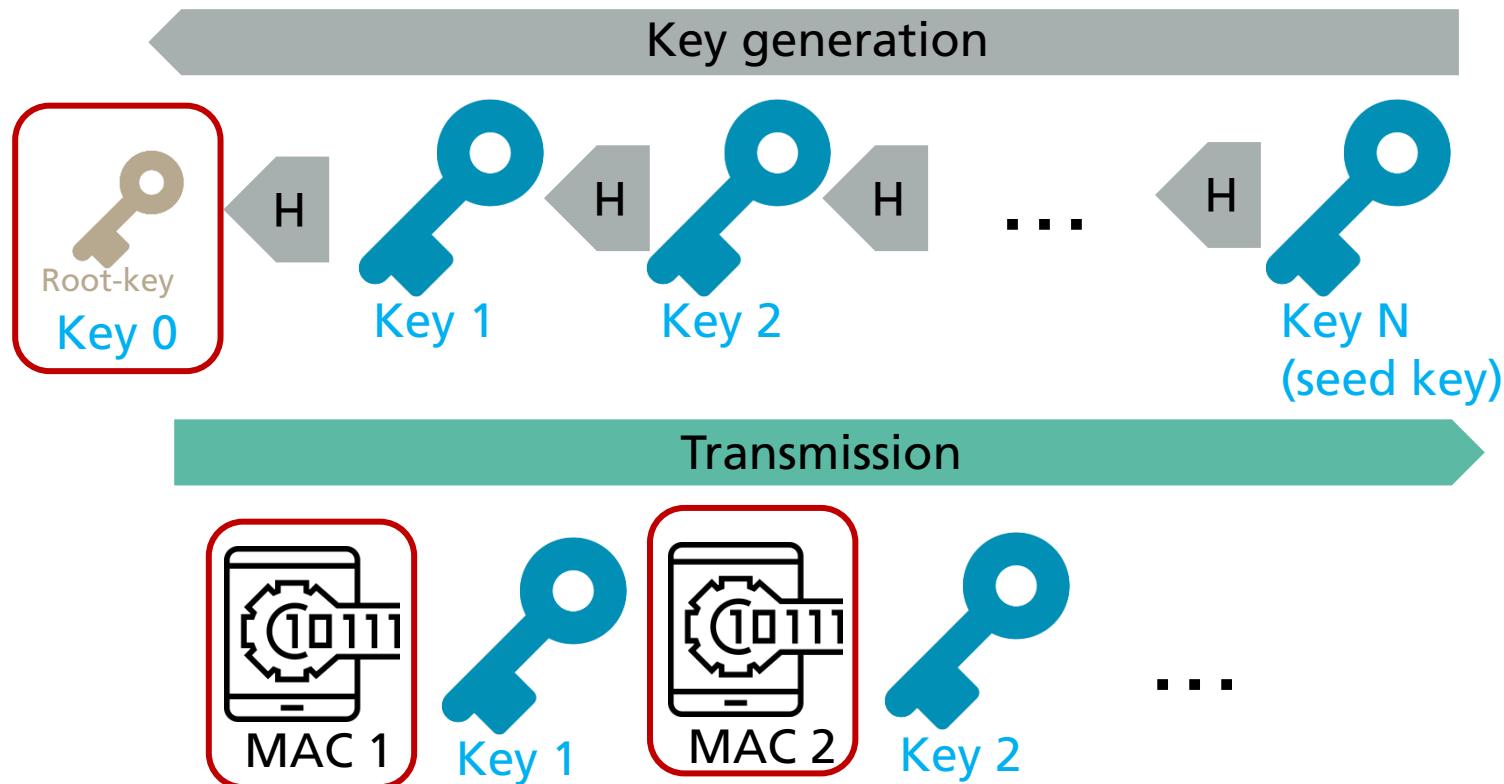
- Introduction to OS-NMA
- Implementation
- Advantages, disadvantages, constraints, and dangers

Open Service Navigation Message Authentication (OS-NMA)



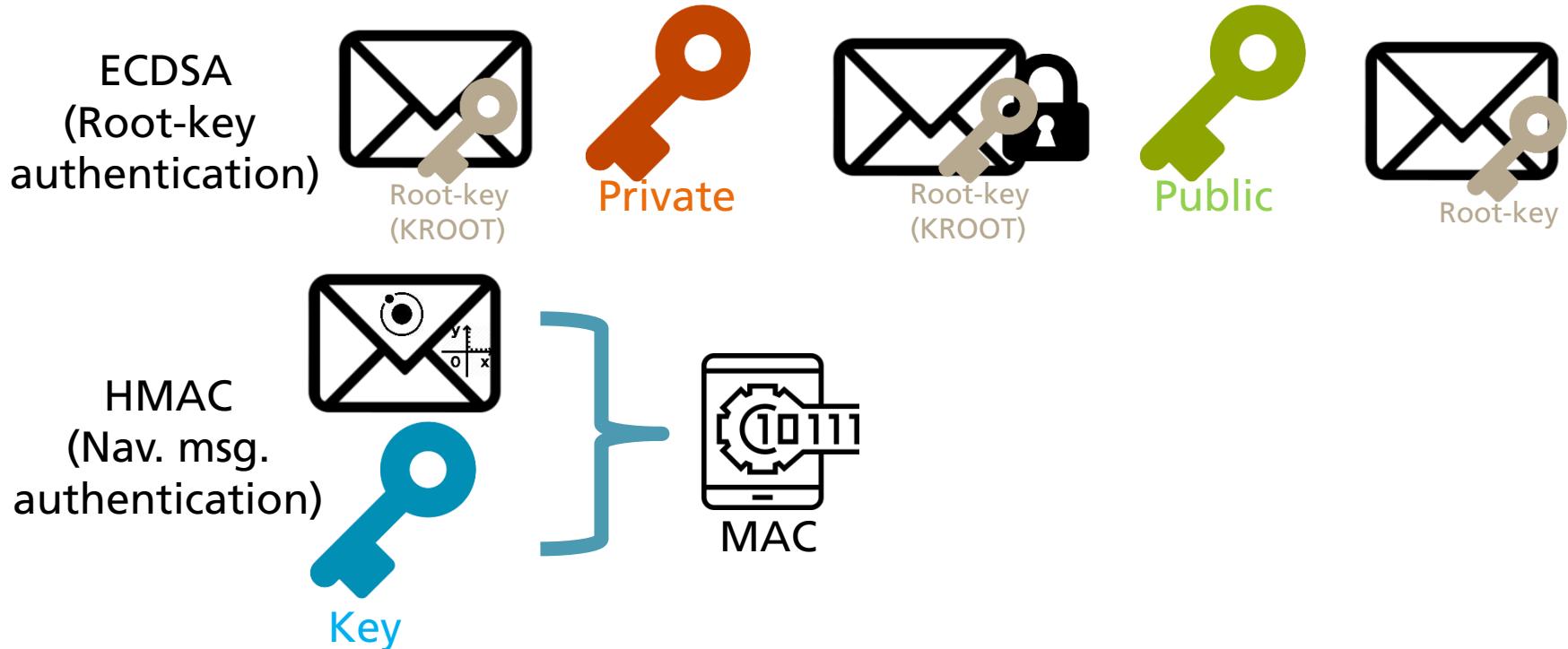
OS-NMA: A brief description

- Timed Efficient Stream Loss-tolerant Authentication (TESLA)
- 1) Root key verifies all keys
- 2) Each key verify the previous Message Authentication Code (MAC)



OS-NMA: A brief description

- Assymetrical cryptography (slow, done only once)
 - Elliptic Curve Digital Signature Algorithm (ECDSA) → 448-1043 bits
- Symmetrical cryptography (fast, done for key / MAC generation)
 - Hash-based message authentication code (HMAC) → 256 bits → Truncate

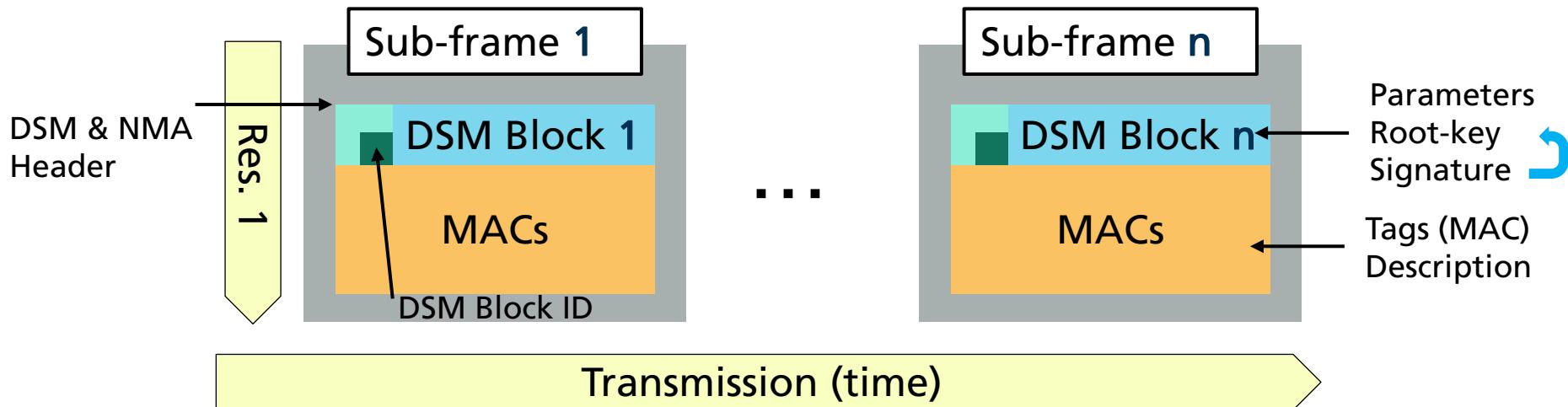


OS-NMA: A brief description

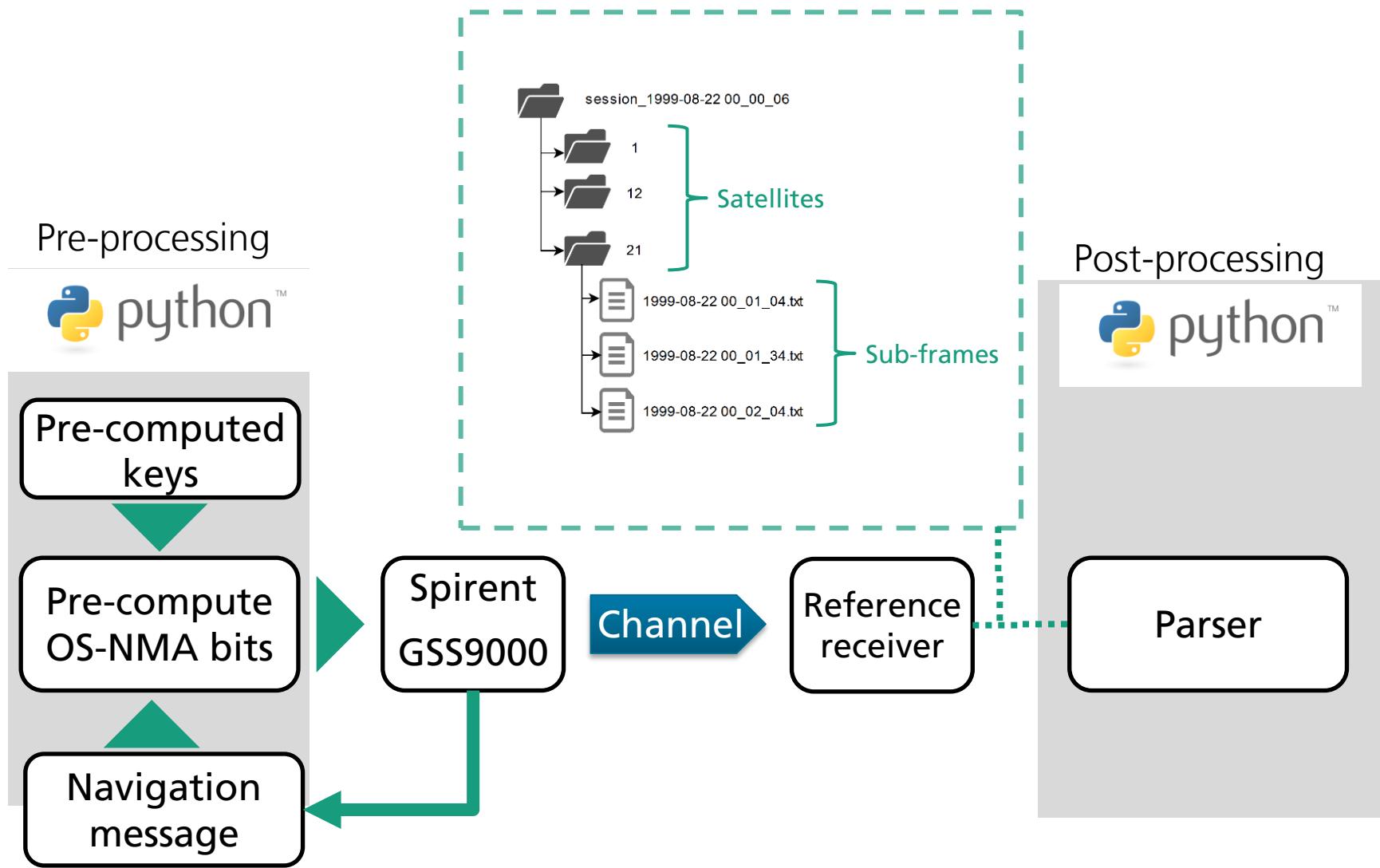
E1-B								
Even/odd=1	Page Type	Data j (2/2)	OSNMA	SAR	Spare	CRC _j	Reserved 2	Tail
1	1	16	40	22	2	24	8	6
								Total (bits) 120

E1-B				
Even/odd=0	Page Type	Data k (1/2)	Tail	Total (bits)
1	1	112	6	120

- I/NAV: 40 bits every 2 seconds
- Subframe : 600 bits (40 bits x 15 pages)
- **Header & Root-key (HKROOT)**: 120 bits (!)
 - Header
 - Digital Signature Message (DSM) Block
 - 6 - 16 subframes (3 to 8 minutes)
- **MAC section** : 480 bits
 - Contains the signatures



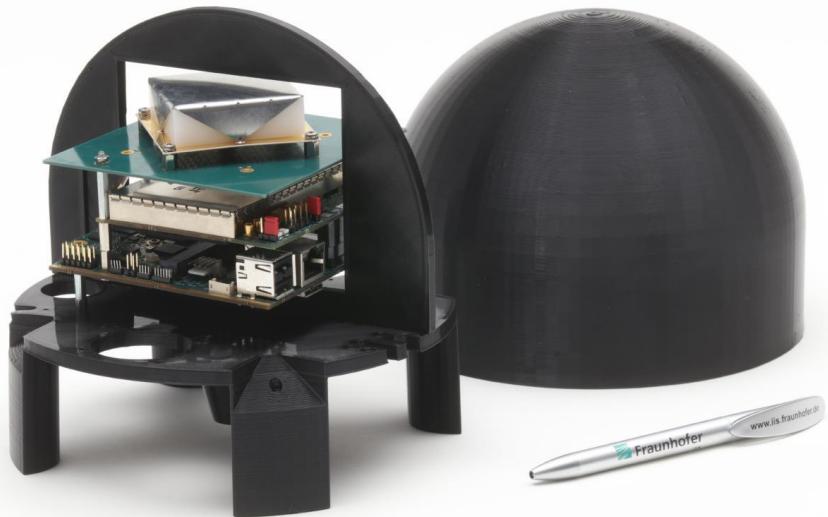
Implementation set-up



Receiver Independent

- Raw navigation message bits available:

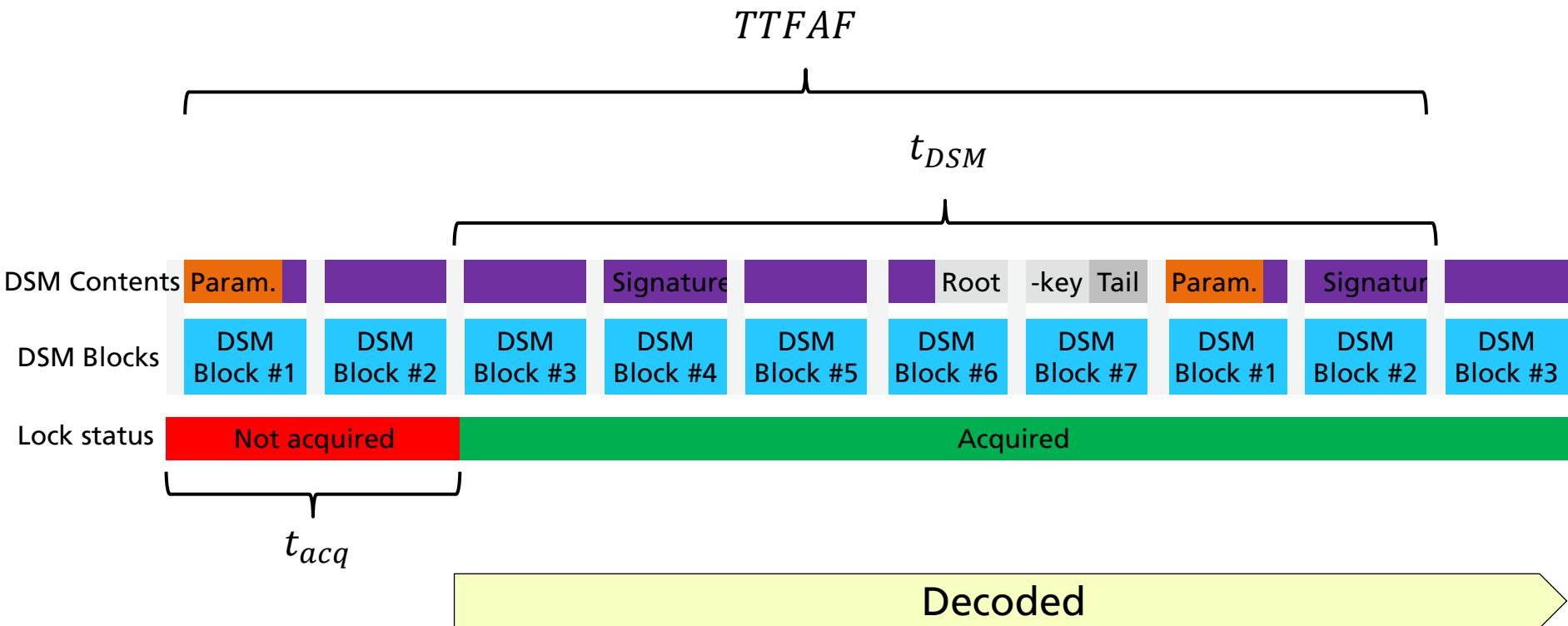
Manufacturer	Receiver	Raw bits
Septentrio	PolaRx5	Accessible as GalRawINAV
u-blox	M8T	Accessible in UBX-RXM-SFRBX
Fraunhofer IIS	GOOSE	Custom direct write to file
Android	Selected smartphones	Accessible in GNSS Raw Data*



*From API 24 onwards

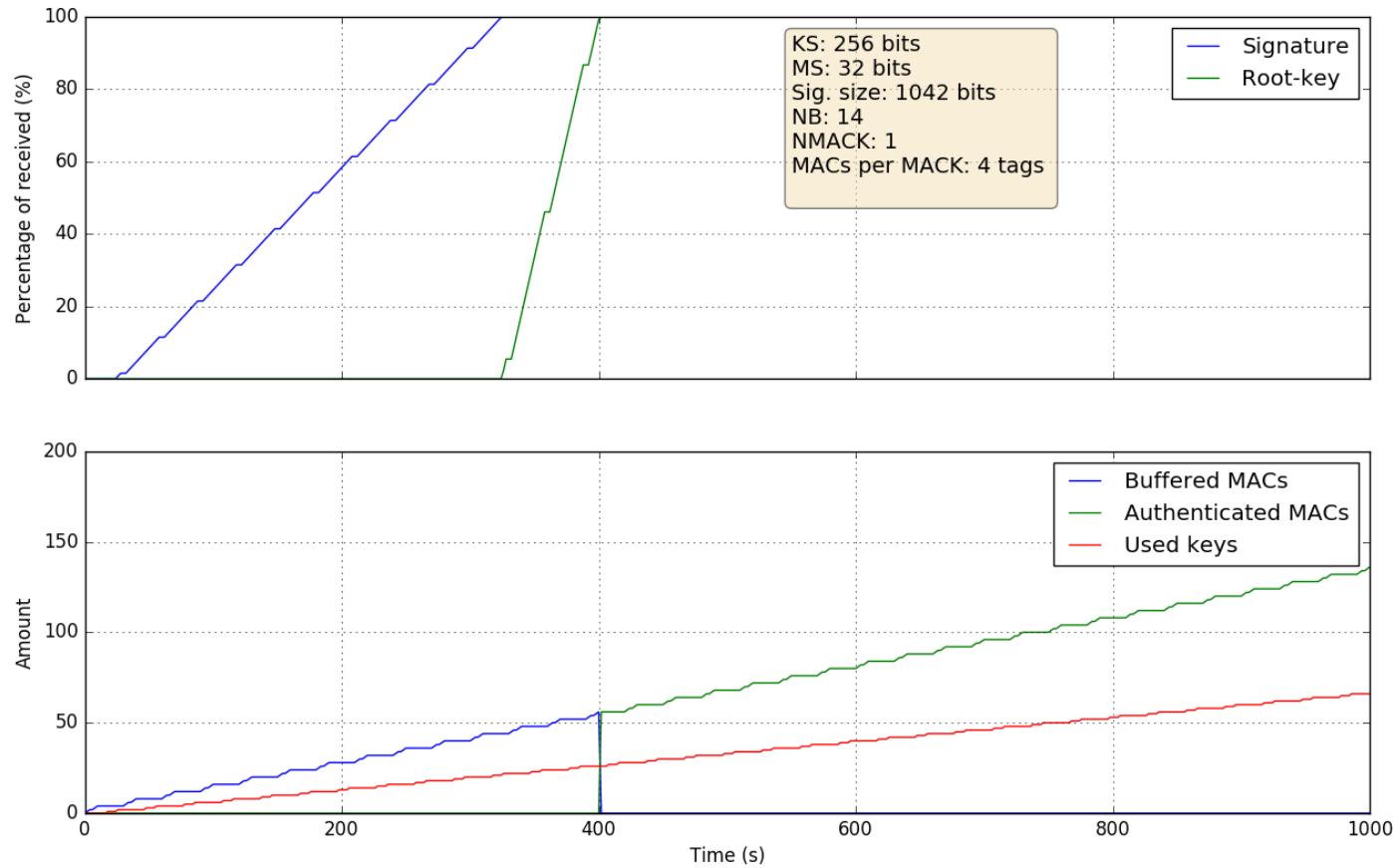
Constraints: Time

- Time to First Authenticated Fix (TTFAF)
- From cold-start



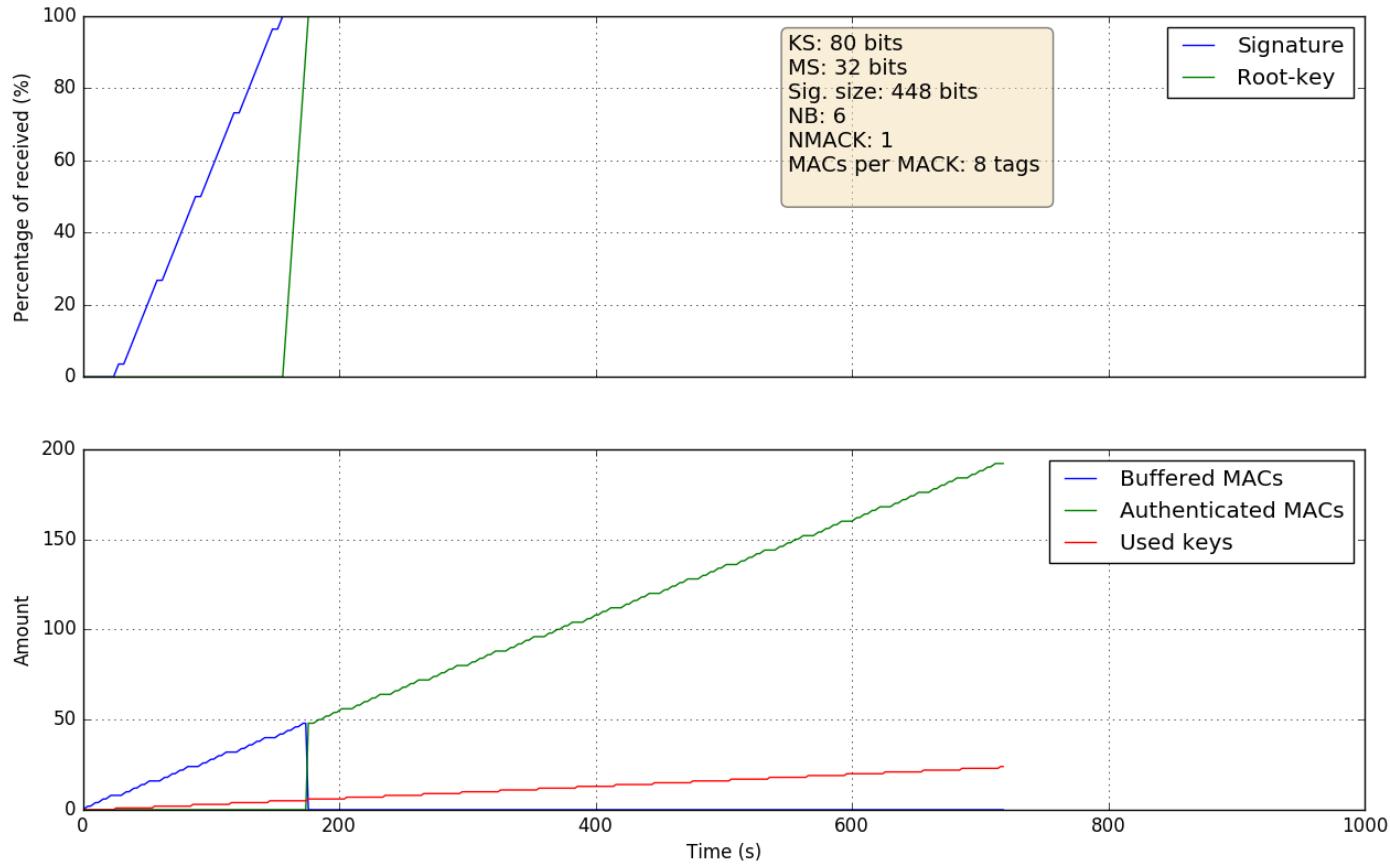
Constraints: Time

- Slowest case ca. 420 seconds



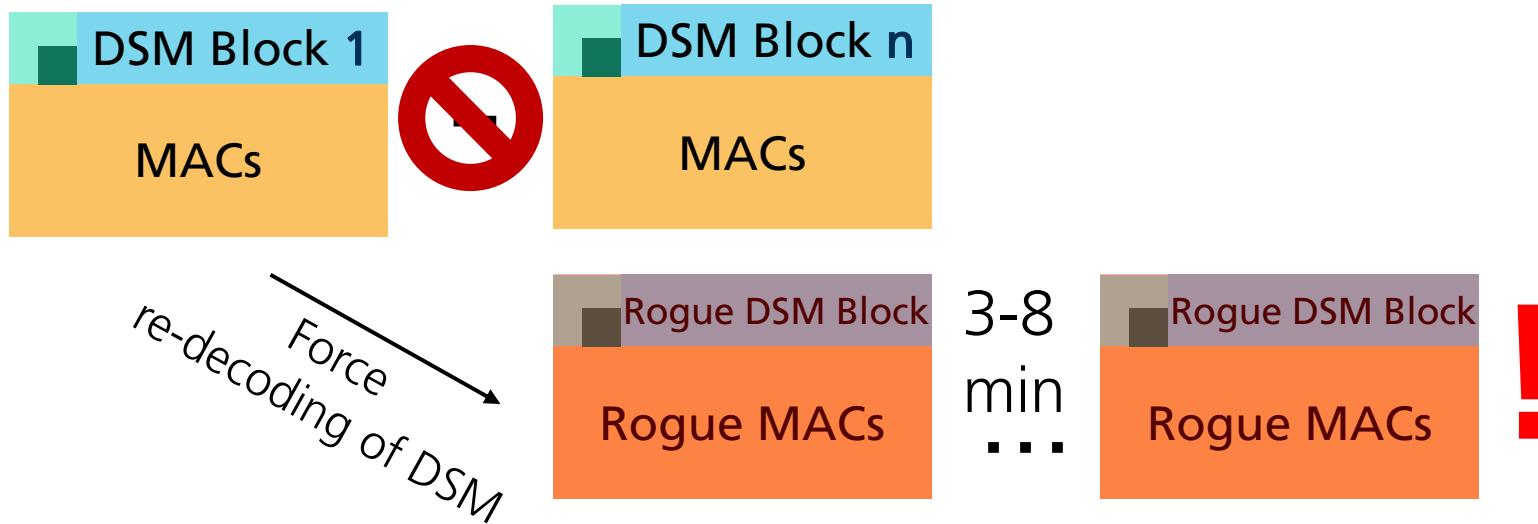
Constraints: Time

- Fastest case 180 seconds (from cold start)

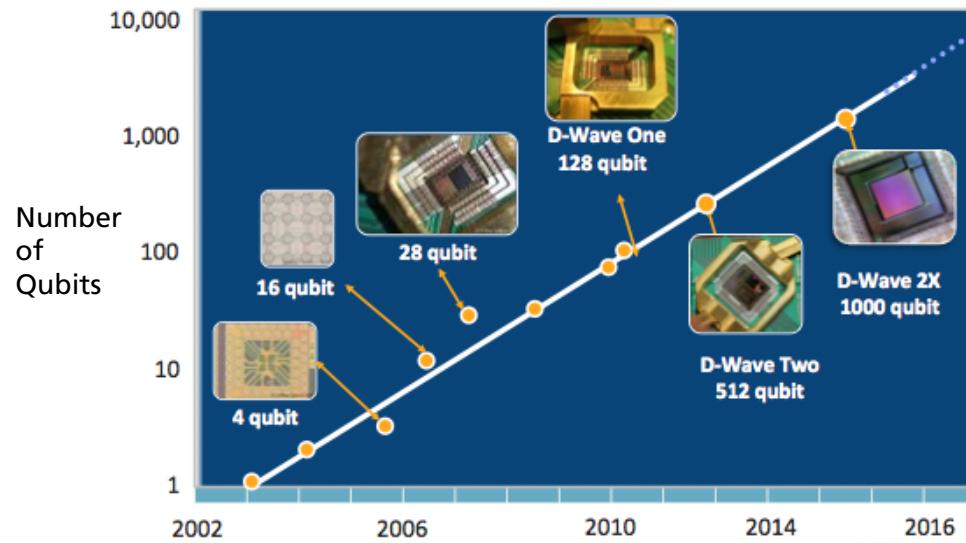


Constraints: Time to first alert

- Deny the signal and force re-decoding
- Avoided pre-trusting keys

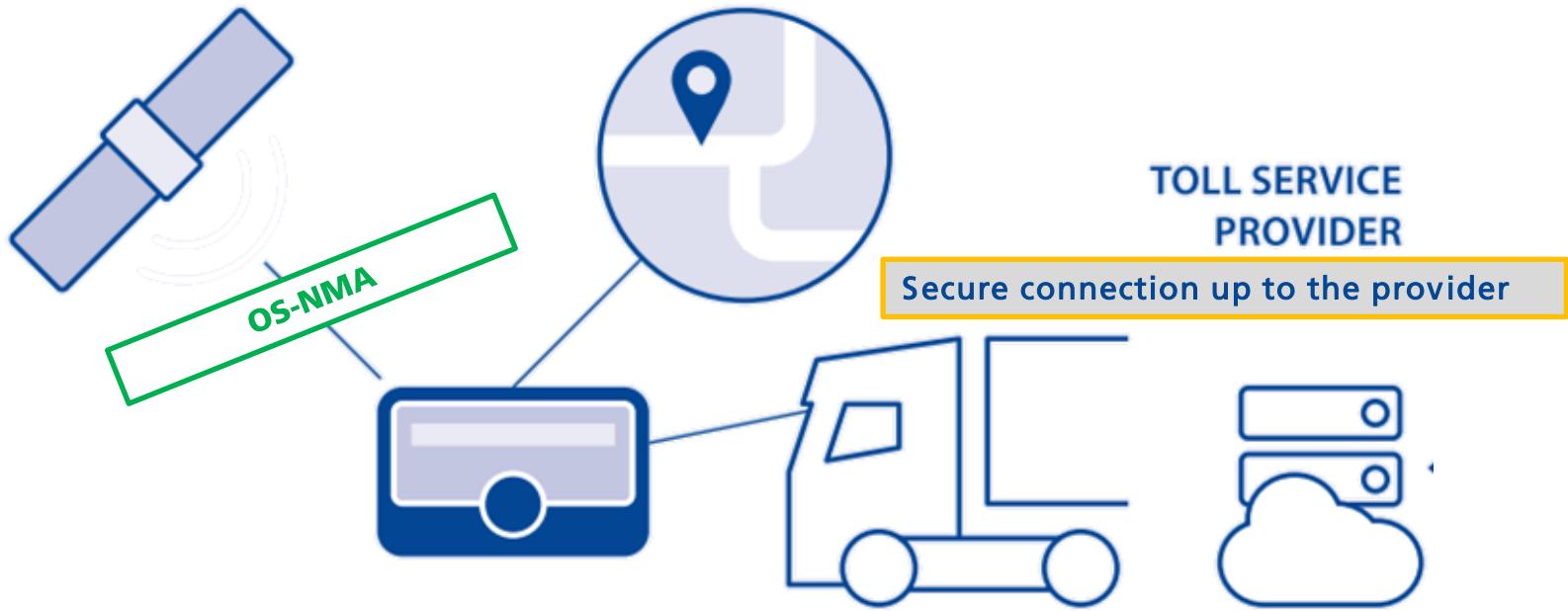


Constraints: Security of algorithms



- Symmetric cryptography → Hashing is quantum safe
- Asymmetric cryptography → ECDSA is **not** quantum safe!

Use-cases



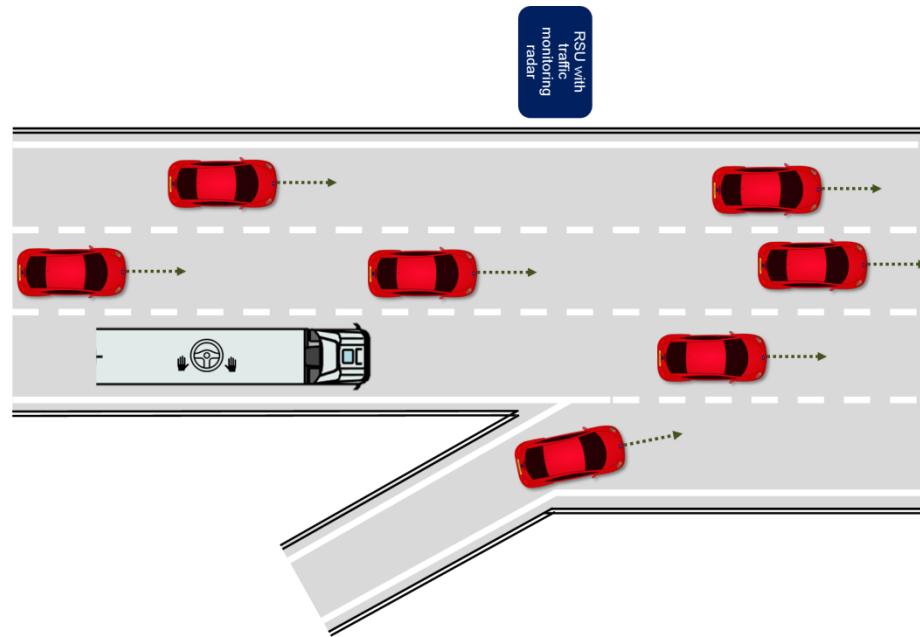
Source: ©Rocca74



Source: ©Vladimir Beznakov

Use-cases: Project PRoPART

- The main objective of the PRoPART is to **develop and demonstrate a high availability positioning solution for connected automated driving applications.**
- enhance an existing RTK (Real Time Kinematic) software solution by **exploiting the distinguished features of Galileo signals**



Conclusions: Why / why not OS-NMA?



Open Service



Secure nav. msg.



Low impact on TTF(A)F*



Firmware update only



Ground segment



Long time to alarm



Replay attacks



Spreading authentication

THANK YOU!

Questions?

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